

Deforming and Animating Multi-Material Objects Using Multi-Valued Field Functions



*Examples of phenomena that can be modeled using multiple field functions: Skinning [Vaillant13],
Garment layers in contact [Buffet19], volcano lava (real photograph).*

Place: LIX/Ecole Polytechnique, Palaiseau. VISTA team.

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Contract duration : 36 months, starting at Fall 2023.

Context.

3D objects are often represented by meshes, enabling fast rendering of 3D scenes, but this representation becomes ineffective when volume or contact deformations of colliding objects are to be precisely controlled. They also lack robustness when the internal structure is complex and the object topology is to change over time. In these cases, volume-based representations such as 3D field functions are particularly adapted to represent, not only volumes, but density of material, in associating a scalar value to every position in space depending on the presence of material. The object surface can then be defined as an implicit surface (for instance the iso-surface where the field function is null), its inside being located where the function is larger than the iso-value (positive) and the outside where it is lower (negative).

The use of field functions is particularly well suited for assembling objects parts in a simple and unified manner while automatically handling changes in topology. They also explicitly represent both the objects inside and outside. These volume-based representations, initially developed in the 90's [Blumenthal97] are attracting a lot of attention in recent years for their ability to robustly represent arbitrary shapes whose embedding can be learned [JoonPark19, Sharp22], or as a way to provide an adapted representation for massively detailed, yet interactive, natural sceneries (terrains [Paris19], volcano eruption [Stora99, Lastic22], bio-inspired shapes

[Garnier22], etc), or for sketch-based shape modeling allowing art controllability [Angles17] using advanced blending operators [Gourmel13].

A particular interest of field function is their ability to efficiently detect collisions between different materials, and respond in modeling contact surfaces whose properties can be expressed via blending operators. This ability was explored to handle surface contacts in skinning deformation while preserving local details encoded with their respective field-value [Vaillant13-14], as well as solving collision for an arbitrary number of interleaved garments layers on top of each other for clothing application [Buffet19]. A key aspect of these approaches is to not only consider the surface as an isovalue of an arbitrary field, but to make use of the values of the field in space also beyond the iso-set in order to preserve details or model spatial interactions at distance.

Objective

This PhD aims at extending field-based operators toward animated complex multi-material. We want to explore the full potential of field functions where blending and/or self-compositing is to depend on the values of different fields modeling different materials, as well as on multi-valued fields representing the space-varying parameters of a given material.

This can be, for instance, used to animate a lava flow whose inner field value corresponds to the local temperature, and for which different inner behaviors are expected by range of temperature. In such cases, varying blending operators could be defined in order to handle collision, such as a contact operator where the crust is already solidified, versus soft blending to model the merging behavior of the underneath hot fluid layers. More generally, this methodology could benefit the animation of material exhibiting multi-phasic behavior from a liquid phase with various viscosity to granular and solid behavior (sand with different proportions of water, mud, snow...)

Another application could be to handle various levels of details in different fields in order to model highly detailed shapes. In such cases, some fields may carry texture-like details that will be expressed and blended differently depending on their environment. This may for instance be used to model organic shapes with details automatically adapting to their respective position, to branching structures and contact with other organs.

Context of the position

The successful candidate to this PhD will be hired by Ecole Polytechnique, and integrate the VISTA research team at LIX/CNRS (Laboratoire d'Informatique de l'Ecole Polytechnique) in Palaiseau. We offer a high-standard research environment (including facilities and equipment), within the vibrant academic and industrial environment of Institut Polytechnique de Paris.

This PhD will take place in the context of the ANR MultiForm, involving LIX/Ecole Polytechnique, IRIT/Université Paul Sabatier, LORIA/Université de Lorraine. The student hired on this PhD will benefit from the ANR funding dedicated to this project to develop his/her research. This funding

includes regular meetings with the partner Universities, with the possibility of on-site exchange to benefit from partners expertise, engineering development, academic and industrial contacts.

The PhD will also benefit from dedicated access to the technical platforms developed by the partners such as the “Implicit Blending Library” [Gourmel13], “Radium Engine” [Radium] for efficient animation development, or the “Matisse” [Bernhardt08] software implementing implicit modeling tools for browsers.

Requirements and application

Candidate to this PhD must be:

- About to graduate (or recently graduated) from a Master level in Computer Science.
- Skilled in programming: Compiled languages such as C++, and possibly script languages such as Python, or C# in Unity as a supplement.
- Relevant good background in Computer Graphics such as 3D modeling, 3D Animation, Implicit Surface. Please detail this background experience in your application.

Please send your application to Damien Rohmer (Damien.Rohmer@polytechnique.edu) and Marie-Paule Cani (Marie-Paule.Cani@polytechnique.edu) with the following elements:

- Curriculum (please state clearly your Diplomas and field of study, previous experiences/internships, and current position).
- Motivation Letter
- Copy of your Master transcript
- Recommendation letter, or at least a possible referent that knows you, and working in Computer Graphics research or related field.

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